Lumenier Pill LED Betaflight Configuration

Pre-requisites:

- LED power wires should be properly soldered to pads that provide the correct voltage. It is recommended to solder the LED power wires directly to the ESC battery pads: 3S to 6S ONLY.
- LED signal wire should be soldered to a pad in the flight controller that have a "timer" such as: LED pad, Motor pads, Servo pads.
- Flash your quad with the latest Betaflight firmware making sure you select the "Servos" and "LED Strip" options. *Figure 0-1*

0			
			Please do not try to flash non-Betaflight hardware with this firmware fla
			Do not disconnect the board or turn off your computer while flashing.
	Autodetect	0	Note: STM32 bootloader is stored in ROM, it cannot be bricked. Note: Auto-Connect is always disabled while you are inside firmware fla
	Auto-Getect	9	Note: Make sure you have a backup; some upgrades/downgrades will wi
-			Note: If you have problems flashing try disconnecting all cables from y Note: When flashing boards that have directly connected USB sockets (m
			have the correct software and drivers installed
			IMPORTANT: Ensure you flash a file appropriate for your target. Flashing
0			
			Build Configuration
			Telemetry Protocol
			V O Automatically Included
			Motor Protocol
(SD)	×OSD (HD)	×Pin	
			0
			Release and Build info
			Persuany / Long communication
			Recovery / Lost communication
low the	se steps to restor	re com	
	(SD)	✓ Ø ✓ Ø ✓ Ø Ø Ø Ø Ø Ø Ø Ø Ø	 ✓ Ø ✓ Ø ✓ Ø Ø Ø Ø Ø Ø

Figure 0-1

Example using the LED pad on the Flight Controller

1.1 Solder The LED signal wire to the LED pad in the Flight Controller.

1.2 Go to the CLI and type: RESOURCE and the hit enter. Figure 1-2.

1.3 Find the pins for the LED_STRIP 1 (A08) and SERVO 1 (E05) and write then down. *Figure 1-3.*

NOTE: in this example A08 is assigned to the LED_STRIP 1 and E05 to the SERVO 1. THESE pins will be different in your Flight Controller

BETAFI Configurator: 10.10 Firmware: 4.5.1 BT Target: MTKS/MATE).0 (c97deaf)	on ittery	Entering CLI Mode, type
Configurator: 10.10 Firmware: 4.5.1 BT	10 (c97deaf) FL KH743(STM32H743)		Entering CLI Mode, type # # Building AutoComplete # # Building AutoComplete # resource BEEPER 1 A15 resource MOTOR 1 B00 resource MOTOR 2 B01 resource MOTOR 3 A00 resource MOTOR 3 A01 resource MOTOR 4 A01 resource MOTOR 5 A02 resource MOTOR 6 A03 resource MOTOR 7 D12 resource MOTOR 7 D12 resource SERVO 1 E05 resource SERVO 1 E05 resource SERVO 1 E05 resource SERVA 2 E06 resource SERIAL_TX 1 A09 resource SERIAL_TX 1 A09 resource SERIAL_TX 1 A09 resource SERIAL_TX 4 B09 resource SERIAL_TX 7 E08 resource SERIAL_TX 8 E01 resource SERIAL_RX 3 D09 resource SERIAL_RX 3 D09 resource SERIAL_RX 4 B08 resource SERIAL_RX 4 B08 resource SERIAL_RX 7 E07 resource SERIAL_RX 7 E07 resource SERIAL_RX 8 E00 resource SERIAL_RX 8 E00 resource SERIAL_RX 8 E00 resource I2C_SCL 1 B06 resource I2C_SCL 2 B10 resource I2C_SDA 2 B11 resource LED 1 E03 resource LED 2 E04
	resource Figure 1-2		resource LED 2 E04 resource SPI_SCK 1 A05 resource SPI_SCK 2 B13 resource SPI_SCK 3 B03 resource SPI_SCK 4 E12 resource SPI_SDI 1 A06 resource SPI_SDI 2 B14 Write your command her

Figure 1-3

1.4 Free both resources by typing in the CLI: resource led_strip none and then hit enter. Figure 1-4.

1.4.1 Repeat the previous step for the servo 1: resource servo 1 none Figure 1-5.



Figure 1-4

Figure 1-5

1.8 Re-assign the **pin A08** (pin will be different in your setup) to serve 1 by typing: resource servo 1 A08.

Figure 1-6.

1.9 type "save" and press enter Figure 1-7.

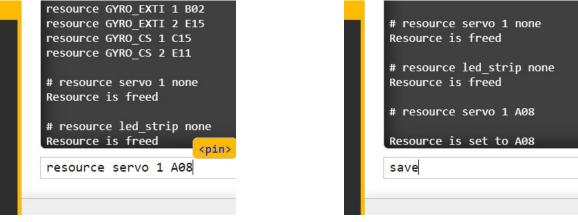


Figure 1-6

Figure 1-7

1.8 Go to the "SERVOS" tab in Betaflight Configurator and select the channel where you have assigned your 3-position switch. In this example Aux 2 channel have been assigned for the 3-position switch. Make sure you select the channel in the corresponding SERVO 1 row.

Figure 1-8.

1.9 Type the correct parameters in the MIN, MID, and MAX taps for the functions of the LED: *Figure 1-8.* (blue marks)

50% power: 1100 +/- 55 100% power: 1300 +/- 65 OFF: 1500 +/- 75 Strobe: 1800 +/- 90

1.10 Plug your battery in and run a test. You should see the servo channel 1 moving when you flip the 3-position switch back and forth and your LED turning ON and OFF. *Figure 1-8.* (Green arrow)

orts	Servos																				w
onfiguration							Cha	nge Dire	ction	TX To M	atch										
ower & Battery	Servo 1	1350 \$	1500 \$	1720 \$	CH1		0	0	- 1	2	•••	0	AC	A6	0	••		010		0	Rate: 100%
esets	Servo 2	1000 \$	1500 🗘	2000 3					0										D	0	Rate: 100%
Tuning	Servo 3	1000 \$	1500 \$	2000 🗘			0	0			0	0		0	0		0	0		0	Rate: 100%
eiver	Servo 4	1000 \$	1500 \$	2000 \$		0	0		0			0	0		0	0		0		0	Rate: 100%
les	Servo 5	1000 \$	1500 \$	2000 \$							0			0				0		0	Rate: 100%
stments	Servo 6	1000 \$	1500 🗘	2000 🗘	0	0	0		0	0		0	0			0	0		0	0	Rate: 100%
25	Servo 7	1000 \$	1500 \$	2000 \$	0				0	0	0				0			0		0	Rate: 100%
vrs	Servo 8	1000 🗘	1500 \$	2000 \$	0	0	0	0	0	0		0	0	0	0	0		0	0	0	Rate: 100%
sors sered Logging kbox	1 2	3 4	Servos 5 6	7	8	1															

Figure 1-8